

Dynamic Element Textures

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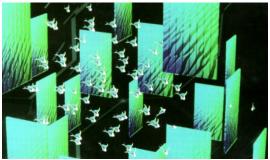


Aggregated elements



Computer animation

- Physics based simulation
 Visual realism
 X Lack of artistic control
 X Application-specific
- Manual edit
 - Intuitive control
 - $\boldsymbol{\times}$ Tedious for complex scenes



[Reynolds 1987]

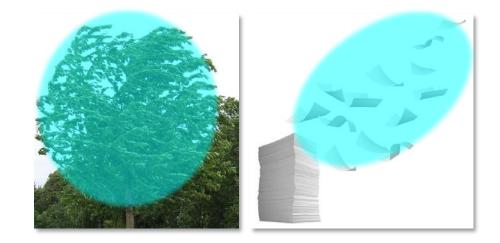


[Hsu and Keyser 2012]

Key observations

Many natural phenomena

• Large scale structures



Key observations

Many natural phenomena

• Large scale structures

- Small scale details
 - Spatial-temporal repetitions
 - Random variations



Our approach

Many natural phenomena

• Large scale structures

Dynamic element textures

- Output constraints
 - Constrained optimization

- Small scale details
 - Spatial-temporal repetitions
 - Random variations

Input exemplars
 Data-driven computation

Technical challenges

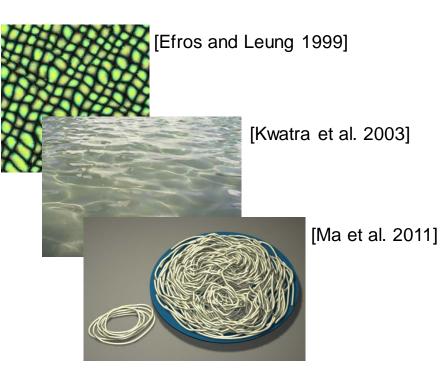
- Representation
 - Diversity of natural phenomena
- Input analysis
 - Coupled global structure and local details
- Output synthesis
 - Different controls
 - High dimensional state space

Related work: texture

• Neighborhood-base texture synthesis

• Time-varying textures

• Element-based textures

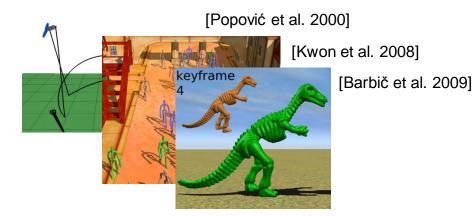


Related work: animation

- Data-driven synthesis
 - Character
 - Mesh ensemble
 - Cloth wrinkles



- Controllable synthesis
 - Rigid body
 - Crowd formation
 - Deformable objects



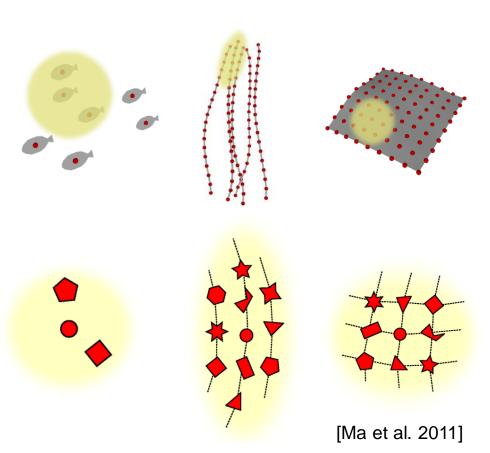
Core ideas

• Spatial-temporal samples

$$\mathbf{u}(s) = \big(\mathbf{p}(s), t(s)\big)$$

• Neighborhood

$$\mathbf{n}(s) = \{\widehat{\mathbf{u}}(s', s)\}\$$
$$= \{\mathbf{u}(s') - \mathbf{u}(s)\}\$$



Core ideas

Spatial-temporal samples

 $\mathbf{u}(s) = \big(\mathbf{p}(s), t(s)\big)$

• Neighborhood

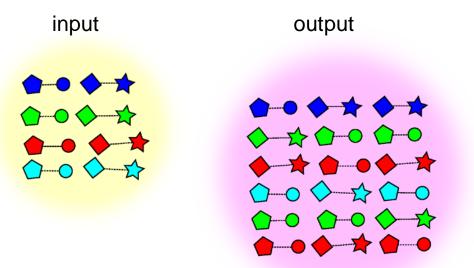
 $\mathbf{n}(s) = \{\widehat{\mathbf{u}}(s', s)\}\$ $= \{\mathbf{u}(s') - \mathbf{u}(s)\}\$

• Distance measure

 $|\mathbf{n}(s_o) - \mathbf{n}(s_i)|^2$

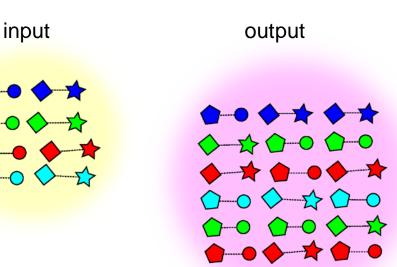
[Ma et al. 2011] space 💋 🏠 o 🔶 🖈 time 🛑 _s🗨 \diamond \bigcirc $() \circ \diamond \Rightarrow$ whole neigh. compact neigh.

- Initialization
 - Random patch copy



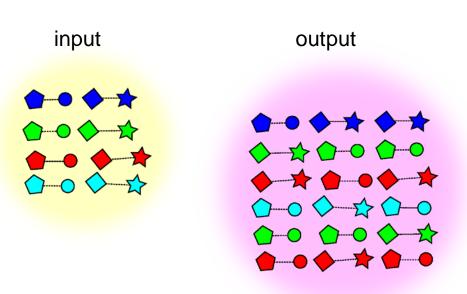
- Initialization
 - Random patch copy

Iterative optimization
 – [Kwatra et al. 2003]

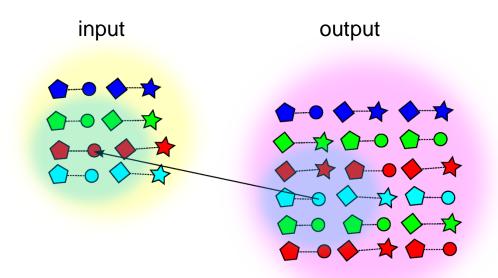


- Initialization
 - Random patch copy
- Search step

• Assignment step



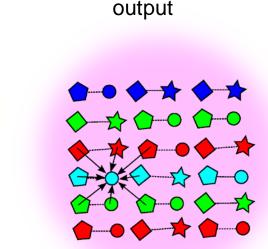
- Initialization
 - Random patch copy
- Search step
 - Nearest neighbor
- Assignment step



- Initialization
 - Random patch copy
- Search step
 - Nearest neighbor

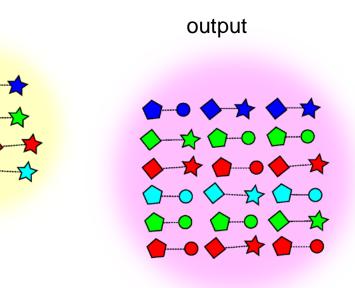
input

- Assignment step
 - Least squares

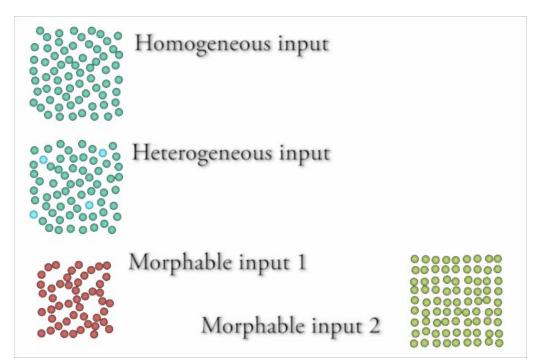


input

- Initialization
 - Random patch copy
- Search step
 Nearest neighbor
 Assignment step
 - Least squares



- Initialization
 - Random patch copy
- Search step
 - Nearest neighbor
- Assignment step
 - Least squares



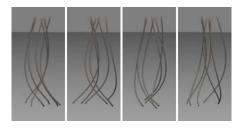
Algorithm: smooth synthesis

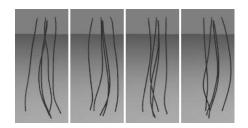
- Goal: reduce jittering artifact
- Approach
 - Gaussian falloff
 - Multiple nearest neighbors
 - Adaptive interpolation

Algorithm: smooth synthesis

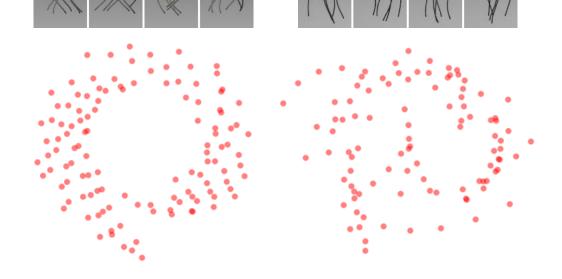
- Goal: reduce jittering artifact
- Approach
 - Gaussian falloff

- Non-smooth synthesis Smooth synthesis
- Multiple nearest neighbors
- Adaptive interpolation



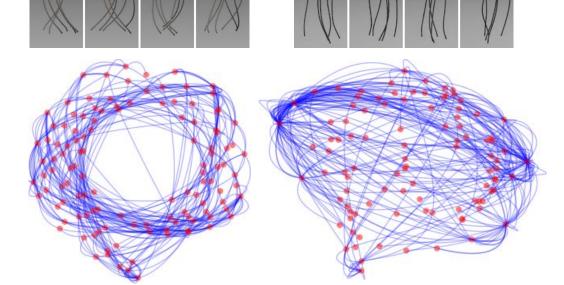


- Approach
 - Graph construction

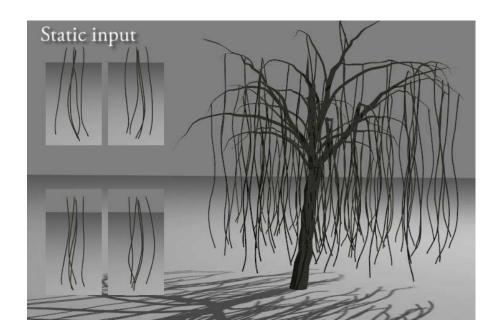


VA1

- Approach
 - Graph construction
 - Path computation



- Approach
 - Graph construction
 - Path computation



- Goal: decompose general inputs
 - Global structure
 - Local details

- Approach
 - Low-pass filtering

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Original input



Analysis result (small kernel)

- Goal: decompose general inputs
 - Global structure
 - Local details

- Approach
 - Low-pass filtering



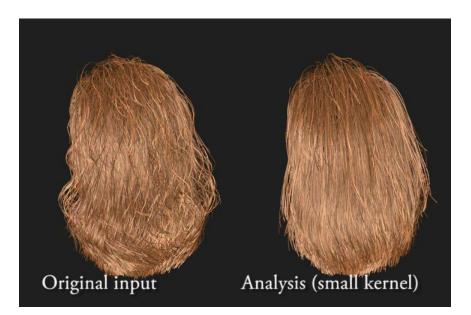
Original input



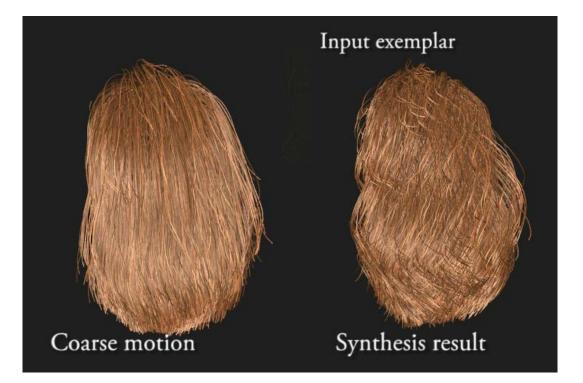
(large kernel)

- Goal: decompose general inputs
 - Global structure
 - Local details

- Approach
 - Low-pass filtering



Results: hair synthesis



Results: fish

• Homogeneous

- Temporally-heterogeneous
- Spatially-heterogeneous

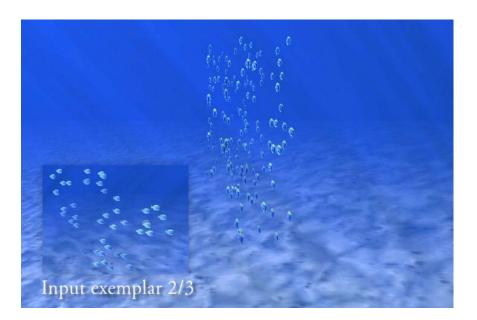


Results: fish

• Homogeneous

• Temporally-heterogeneous

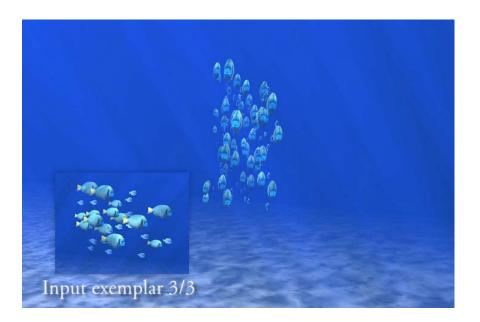
• Spatially-heterogeneous



Results: fish

• Homogeneous

- Temporally-heterogeneous
- Spatially-heterogeneous



Results: noodles

• Realistic

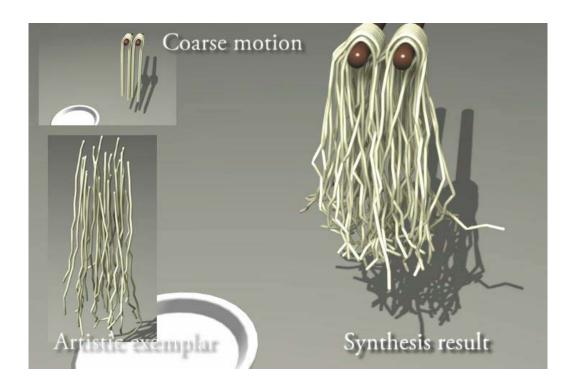
• Artistic

Coarse motion	
Simulated exemptor	Synthesis result

Results: noodles

Realistic

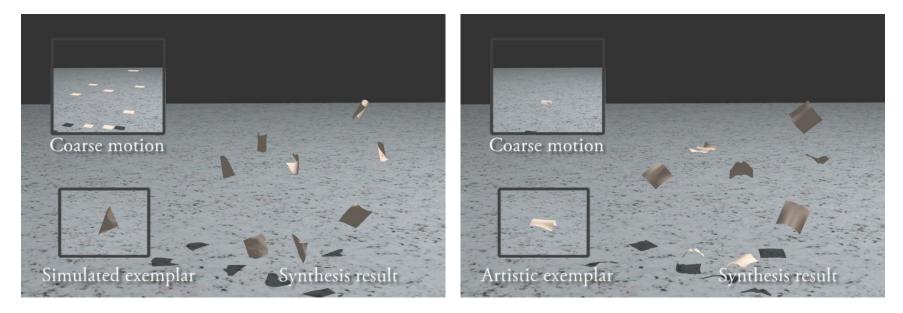
• Artistic



Results: scraps

Realistic

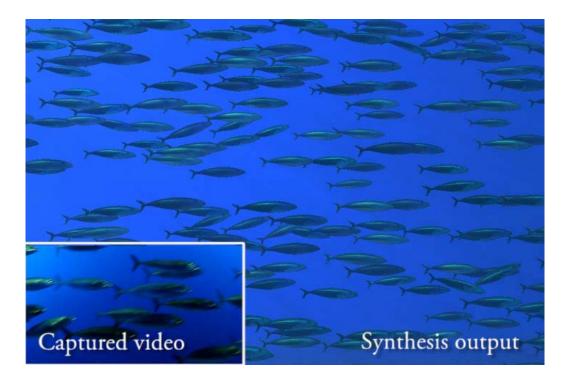
Artistic



Results: captured input

• Video input

• Image input

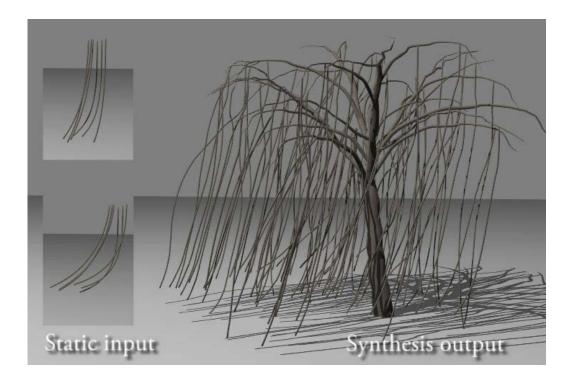


Results: captured input

• Video input

• Image input





Conclusion

• A general representation for spatial-temporal repetitions

• A synthesis framework with both coarse scale and fine scale control

• An analysis algorithm to decompose general inputs into local and global components

Future work

- Order-independent synthesis for efficiency
 - [Lefebvre and Hoppe SIGGRAPH 2005]

Domain-specific metrics for accurate evaluation
 – [Guy et al. SIGGRAPH Asia 2012; Zheng SCA 2013]

- Authoring UI for human intervention
 - [Kazi et al. SIGCHI 2012]

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Thank you!

Project page (source code available): www.cs.ubc.ca/~chyma/publications/dt/

